



S32 SDK for Power Architecture Release Notes

Version 3.0.1 RTM SR









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1. Description

The S32 Software Development Kit (S32 SDK) is an extensive suite of peripheral drivers, RTOS, stacks and middleware designed to simplify and accelerate application development on NXP MPC574x-B-C-G, MPC574x-P, MPC577xB-E-C, MPC574xR, S32R274 and S32R372 Power Architecture based microcontrollers.

This release has RTM quality status in terms of testing and quality documentation. RTM releases contain all planned features implemented and tested. RTM releases are candidates that can be used in production.

This SDK can be used as is (see Documentation) or it can be used with S32 Design Studio IDE.

Refer to *License(License.txt)* for licensing information and *Software content register(SW-Content-Register-S32-SDK.txt)* for the Software contents of this product. The files can be found in the root of the installation directory.

For support and issue reporting use the following ways of contact:

- NXP Support to https://www.nxp.com/support/support:SUPPORTHOME
- NXP Community https://community.nxp.com/community/s32/s32sdk









2. New in this release

2.1 Drivers

CPU:

 Updated MMU configuration for MPC577x/B/C/E to match the one configured by PEmicro

DECFILTER:

Added driver support for MPC577x/B/C/E and MPC574xR

HSM:

 Driver updated to support new features introduced by HSM Security Firmware Standard. Driver is backward compatible with older firmware versions.

PSI5:

Added support for MPC577x/B/C/E

2.2 Middleware

SBC:

Added support for FS6500 on MPC5744P

2.3 Libraries

AMMCLib:

Added support for all devices supported in the release

sBOOT:

Added support for MPC5744P

2.4 Examples

MPC5748G examples:

Examples were ported to support DEVKIT-MPC5748G PCB RevD SCH RevD1.
 Compatibility with the previous revision is not guaranteed.

AMMCLib:

Added examples for all parts

DECFILTER:

Added examples for MPC5777C and MPC5746R

PSI5:

Added example for MPC5777C

sBoot:

Added example for MPC5744P

SBC:

Added example for MPC5744P









2.5 Fixed from RTM 3.0.0

Component	Description
clock_manager	CLOCK_DRV_GetFreq did not return the correct values for clock frequencies on secondary cores
ctu, documentation	Updated brief description of examples for MPC5744P and S32Rx7x
emios	Add mode OPWMB_FLAGX2 to can be set period when call the function EMIOS_PWM_DRV_SetPeriod
emios	In the OPWMCB mode duty cycle not include deadtime in the case 0% or 100% duty cycle
examples	FreeRTOS S32R372 Debug_RAM configuration used the wrong core in compiler settings (z4 instead of z7)
examples, FreeRTOS	Fix issue where FreeRTOS could not compile when FreeRTOS.h could not be found in the assembler include path. PEx now adds the 'Generated_Code/' directory to the asm include path
flexpwm	FlexPWM configurator was not allowing Prescaler to be configured in the Submodule setup tab
i2c	The problem was that aborting a transfer using I2C_DRV_MasterAbortTransfer function could not have been done safely, as master module could have been disabled in the middle of the transfer, which caused the slave to hold the SDA line forever low and block the I2C bus. The issue was fixed by aborting the transfer at byte boundary. Same issue was fixed for blocking functions in case TIMEOUT occurred.
pins	When calling PINS_DRV_Init, the configuration for EIRQ0 pin was being overridden if another pin with interrupt disabled was configured after EIRQ0 pin.
power_manager	The all clock source will be disabled except FIRC in SAFE mode. SAFE mode entry does not wait for the clock disable/enable process to finish. It only waits for the FIRC bit to be set. This is to ensure that the SAFE mode is entered as quickly as possible. After CPU switches to SAFE mode successfully, some clock sources are not able to disable immediately. User need to wait time until the clock source is disabled.
tdm	TDM was not supported on Cobra and Rainier
timing_pal	For Timing_pal over STM, if the callback is NULL or notification is disabled, the TIMING_GetRemaining and TIMING_GetElapsed return wrong value from the second period.









3. Software Contents

3.1 Drivers

- ADC_SAR
- BCTU
- CLOCK MANAGER
- CMP
- CPU
- CRC
- CTU
- CSE
- DSPI
- DECFILTER
- EDMA
- EIM
- EMIOS
- ENET (FEC)
- EQADC
- ERM
- ESCI
- ETIMER
- FCCU
- FLASH
- FLEXCAN
- FLEXPWM
- HEADER
- HSM (SHE FIRMWARE V.1.0.5)
- I2C
- IGF
- INTERRUPT MANAGER
- LINFLEX (UART)
- MCAN
- OSIF
- MPU
- MPU_E200
- PASS
- PHY
- PINS
- PIT
- POWER MANAGER
- PSI5
- RTC_API
- SAI (I2S)
- SDADC
- SEMA42
- SMPU
- SRX









- STM
- SWI2C
- SWT
- TDM
- USDHC
- WKPU
- ZIPWIRE

3.2 PAL

- ADC_PAL
- CAN PAL
- I2C_PAL
- I2S_PAL
- IC_PAL
- MPU_PAL
- OC_PAL
- PWM_PAL
- SECURITY_PAL
- SPI_PAL
- TIMING PAL
- UART_PAL
- WDG_PAL

3.3 RTOS

FreeRTOS version 10.0.1

3.4 Middleware

- EEE
- FATES
- SDHC
- TCP/IP
- USB
- SBC

3.5 Libraries

- AMMCLIB RTM 1.1.17
- SBOOT RTM 1.0.2









4. Documentation

- Quick start guide available in "doc" folder.
- User and integration manual available at "doc\Start_here.html".
- Driver user manuals available in "doc" folder.
- Release notes for Middleware available in "doc" folder.
- Documentation for the Middleware can be found in the respective folder.









5. Examples

Туре	Name	Description
	adc_pal	Shows the usage of the ADC_PAL
	adc_pal_eqadc	Shows the usage of the ADC_PAL over EQADC
	adc_pal_sdadc	Shows the usage of the ADC_PAL over SDADC
	adc_swtrigger	Shows the usage of the ADC MPC574xx
	ammclib	Shows the integration with AMMCLib
	bctu_trigger	Shows the usage of BCTU cross triggering
	can_pal	Shows the usage of the CAN_PAL
	cmp_dac	Shows how to use CMP with the internal DAC
	crc_checksum	Calculates CRC using the peripheral driver for multiple standards.
	cse_keyconfig	Configures CSE non-volatile keys
	ctu_trigger	This is an application created to demonstrate triggering of a set of multiple ADC conversions via software trigger (SW->CTU->ADC) and hardware trigger via ETIMER (ETIMER->CTU->ADC)
	decfilter	Shows the usage of the DECFILTER driver
Dri.	dspi_master	Shows the usage of the DSPI/SPI module in master mode
Driver examples	dspi_slave	Shows the usage of the DSPI/SPI module in slave mode
ex	edma_transfer	Show multiple usage scenarios of DMA.
amp	eim_injection	Shows the usage of EIM driver
oles	emios_ic	Shows the usage of the eMIOS IC functionality
0,	emios_oc	Shows the usage of the eMIOS OC functionality
	emios_pwm	Shows the usage of the eMIOS PWM functionality
	enet_loopback	Shows the usage of the ENET module configured in loopback
	enet_ping	Shows the usage of the ENET module by implementing an application which responds to ping requests.
	eqadc	Shows the usage of EQADC driver
	erm_report	Shows the usage of ERM driver
	esci_transfer	Shows the usage of ESCI driver
	etimer	Shows the usage of the ETIMER module
	etpu_pwm	Shows the usage of the ETPU module
	fccu_fault_injection	Show the usage of FCCU driver.
	flash_program_erase	Shows the usage of the flash driver how to program or erase the flash memory
	flexpwm_pwm	Shows the usage of the PWM functionality of FlexPWM









hsm_key_config	Demonstrates the non-volatile key update procedure
i2c_pal	Shows the usage of the I2C_PAL
i2c_transfer	Shows the usage of the I2C driver in both master and slave modes.
i2s_pal	Shows the usage of the I2S_PAL
ic_pal	Shows the usage of the I2C_PAL
input_glitch_filter	Shows the usage of the IGF driver
interrupt_control_multicore	Shows the usage of the Interrupt Manager in a multicore environment
linflexd_uart	Shows the usage of LINFlexD_UART driver in interrup based mode
mcan	Shows the usage of MCAN driver.
mpu_e200_memory_protection	Shows the usage of MPU_E200 driver.
mpu_memory_protection	Shows the usage of MPU driver.
mpu_pal_memory_protection	Shows the usage of the MPU_PAL
oc_pal	Shows the usage of the OC_PAL
pass_lock_unlock	Shows the usage of the PASS module
phy_autoneg	Shows the usage of the PHY module with autonegociation
pit_periodic_interrupt	Shows the usage of the PIT
power_mode_switch	Transitions the MCU into all available power modes.
psi5_async_rx	Shows the usage of PSI5 in ASYNCHRONOUS mode with a PSI5-A16CRC-500_1L sensor.
pwm_pal	Shows the usage of PWM_PAL
rtc_alarm	Shows the usage of the RTC
sai_transfer	Shows the usage of the SAI driver in both master and slave modes
sboot	Shows the integration with sBoot
sbc_fs65	Shows the integration with FS6500 SBC
sdadc_swtrigger	Shows the usage of the SDADC driver
security_pal	Shows the usage of the SECURITY_PAL
- ·	
sema42_multicore	Shows the usage of SEMA42 driver simultaneous over a available cores
· .	
sema42_multicore	available cores Shows how to configure SMPU to protect a region of
sema42_multicore smpu_protection spi_pal	available cores Shows how to configure SMPU to protect a region of memory Shows the usage of the SPI_PAL
sema42_multicore smpu_protection	available cores Shows how to configure SMPU to protect a region of memory









	stm_periodic_interrupt	Shows the usage of the STM
	swi2c_master	Shows the usage of the SWI2C
	swt_interrupt	Shows the usage of the SWT
	timing_pal	Shows the usage of the TIMING_PAL
	uart_pal_echo	Shows the usage of UART PAL over LinFlexD
	wdg_pal_interrupt	Shows the usage of the WDOG_PAL
	wkpu_interrupt	Shows the usage of the WKPU driver
	zipwire_master	Shows the usage of the zipwire driver, configured as LFAST master – works in conjunction with zipwire_slave.
	zipwire_slave	Shows the usage of the zipwire driver, configured as LFAST slave – works in conjunction with zipwire_master.
	eeprom_emulation	Shows basic use cases of the EEPROM Emulation middleware
	flexcan	Shows the usage of FlexCAN driver configured as both bus master and slave
	freertos	Shows the usage of the FreeRTOS MPC574xx
	hello_world	This is a simple application created to show the basic configuration with S32DS
De	hello_world_mkf	This is a simple application created to show the basic configuration with makefile for the supported compilers
Demos	hsm_freertos	Shows the usage of HSM driver using two tasks (one for encryption, one for decryption)
	lwip	Shows the usage of TCP IP stack
	sdhc_fatfs	Shows the usage of FAT FS over uSDHC driver
	sdhc_freertos	Shows the usage of SHDC with FATFS over FreeRTOS
	usb_msd_fatfs	This is a simple FATFS application created to access USB mass storage device
	usb_cdc_lwip	Shows the usage of the TCP/IP stack over USB ethernet









6. Supported hardware and compatible software

6.1 CPUs

- MPC5744B
- MPC5745B
- MPC5746B
- MPC5744C
- MPC5745C
- MPC5746C 1N84S (Cut 2.1)
- MPC5747C
- MPC5748C
- MPC5746G
- MPC5747G
- MPC5748G 0N78S (Cut 3.0)
- MPC5741P
- MPC5742P
- MPC5743P
- MPC5744P 1N15P (Cut 2.2B)
- S32R274 2N58R (Cut 1.2)
- S32R372 0N36U (Cut 1.0)
- SPC5777C 3N45H
- SPC5775B
- SPC5775E
- SPC5746R 1N83M
- SPC5745R
- SPC5743R

The following processor reference manuals have been used:

- MPC5748G RM Rev. 6, 10/2017
- MPC5746C RM Rev. 5, 10/2017
- MPC5744P RM Rev. 6.1, 10/2017
- S32R372 RM Rev. 3.2, 11/2018
- S32R274 RM Rev. 4, 05/2018
- MPC5746R RM Rev. 6.2, 06/2017
- MPC5777C RM Rev. 8.1, 09/2018

The following errata documents were taken into consideration:

- Errata MPC5748G 0N78S.pdf Rev 2 01/2018
- Errata MPC5744P 1N15P.pdf Rev 04/2018
- Errata MPC5746C_1N84S.pdf Rev. 2, 01 2018
- Mask Set Errata for S32R274 Mask 2N58R: S32R274 2N58R.pdf Errata Rev 2
- Mask Set Errata for S32R372 Mask 0N36U: S32R372_0N36U.pdf
- Errata Rev 1 MPC5777CRM Rev. 8.1, 9/2018
- Errata MPC5746R 1N83M Rev. 2.8 10/2018
- Errata MPC5777C_3N45H Rev. 10/2018









6.2 Boards

- DEVKIT-MPC5744P PCB RevX1 SCH RevB
- DEVKIT-MPC5748G PCB RevD SCH RevD1
- Daughter Card MPC574XG-256DS Rev B
- Daughter Card X-MPC574XG-324DS Rev A
- Motherboard X-MPC574XG-MB Rev D
- Daughter Card MPC5744P-257DS Rev B1
- Motherboard MPC57XX Rev C
- S32R274RRUEVB 700-28921 REV B SCH-28921 REV D
- Daughter Card MPC5777C-516DS Rev D
- Daughter Card MPC5746R-252DS Rev A

6.3 Compiler and IDE versions:

- GCC E200 VLE GNU Compiler 4.9.4
 - o 20160726 bld=1607 rev=gceb1328 (1 February 2019)
 - o included in S32DS for Power Architecture 2017 R1
- Green Hills Multi 7.1.4 / Compiler 2017.1.4
- Windriver DIAB Compiler v5.9.6.2

6.4 Debug Probes

- Lauterbach TRACE32 JTAG Debugger
- P&E Multilink (with P&E GDB Server)









7. Known issues and limitations

7.1 S32 Design Studio integration

- Some warnings might be observed after project creation or import.
- Project creation takes a considerable amount of time.
- On multicore projects, it might take a greater amount of time to debug the projects in FLASH target.

7.2 Drivers

CLOCK

 No warning shown for LIN clock constraint not met: "(2/3)* LIN_CLK > interface_clock > 1/3*LIN_CLK"

CRC

- When generating CRC-32 for the ITU-T V.42 standard the user needs to set SWAP_BYTEWISE together with INV and SWAP.
- When generating CRC-16 the user needs to set SWAP_BITWISE bit.

EEE

- The EEE_DRV_ReportEepromStatus() function will return the erasing cycles of the current ACTIVE block. This number is not an accurate value. Because if brownout occurs during updating erase cycle, this erasing cycle will be re-counted from the erase cycle value of the other block.
- The user needs to ensure that *EEE_DRV_MainFunction()* function is called after every write operation. The user can check the status of *g_eraseStatusFlag* global variable after writing data record to decide when needs to call this function.
- When ECC errors occur during the read operation from flash, the driver only supports to get the failing address in the C55FMC ADR register.

EQADC

Digital filter for external triggers cannot be bypassed

FCCU

- For S32R274, S32R372, S32V234, MPC5777C and MPC5746R devices: When
 injecting a fake fault to transition FCCU from Normal to Alarm then to Fault, the time
 configured for Alarm to Fault transition must be lower than the FOSU
 time. Otherwise, FOSU timeout might expire and it will trigger a CPU reset.
- For MPC5777C: The NCF 43 was present if Error Input Pin is pulled down to low signal level.
- When configuring FCCU in debug mode on MPC5746R, it will not initialize properly. Workaround: Set .debugEnable field to false.

FLASH

- It is recommended that the D-cache of the core should be disabled at the initialization code to make sure the program or erase functions work properly.
- Flash controller buffer shall be disabled in the beginning of application for reading and writing to flash.

FLEXPWM

 When using more than one submodule and configuring any of the sub-modules from 1 to 3 to have the reload signal from Master Reload, the LDOK bit for sub-modules 1 to 3 is not cleared. Workaround: The user must make sure to manually clear the









LDOK bit in this situation using the dedicated function: *FLEXPWM_DRV_ClearLDOK*.

I2C

Aborting a transfer with the function I2C_DRV_MasterAbortTransferData() can't be
done safely due to device limitation; there is no way to know the exact stage of the
transfer, and if we disable the module in the middle of the transfer of a character the
slave may hold the SDA line forever low and block the I2C bus. Same situation may
happen if a blocking transfer function is used and TIMEOUT occurs.

IC PAL over FLEXPWM

 When IC PAL is used over FlexPWM with multi-channels combined in mutil-capture modes, the measured result will not work as expected with high frequency as input signal for capture modes.

IC PAL and OC PAL

• PEx component limitation: Multiple PEx components, either IC_PAL or OC_PAL, cannot share the same EMIOS module instance.

LINFLEXD UART

 In DMA mode, bytesRemaining parameter is not always 0 after calling LINFLEXD_UART_GetReceive/TransmitStatus, although all data is successfully transferred.

MPU

MPU driver will not report violation on the EBI Region for MPC5777C.

OC PAL over EMIOS

• Using of internal buses, or bus B, C, D, E with channel 0, 8, 16, 24, respectively, or bus A with channel 23, or bus F with channel 22, must configure period value with the maximum available value of counter register.

PINS

Generation of the pin configuration using the PEx component is slow.

POWER MANAGER

- The core must execute code from RAM memory when switching to a mode in which the flash is in power down or low power state.
- MCU cannot enter STOP0, STANDBY, HALT0 mode while debugger is connected. In addition, STOP0, HALT0, STANBY are not supported while CPU executes code from RAM.
- User does not use the internal ballast in applications using any of the STOP, HALT or STANDBY mode. User must ensure the device is set up to use external ballast (INT_BAL_SELECT pin tied to ground on board). Because the interrupt or wakeup event is activated while transition to HALT, STOP or STANDBY mode, the transition is aborted.
- LPU modes are not supported.
- The driver code will switch to RUN0 mode before entering STOP0 or HALT0 mode from DRUN mode. If CPU is in STOP0, HALT0 and a wake-up signal is detected it will switch to RUN0 mode.
- FXOSC clock source must be turn on in all mode except SAFE mode when CMU is enabled. Before entering SAFE mode, the divider of clock source monitor in CMU should be reset. If the clock condition is not true, CPU will be reset when user switches mode.









PWM PAL over ETIMER

 When generating signals with 0% or 100% duty cycle, a pulse of length equal to one clock tick is generated on the output which has inverted polarity. Consequently, true 0% or 100% duty cycles cannot be achieved.

RTC

 Driver does not support using all prescalers when 32KHz clock is selected. The application should either disable prescalers, or use a higher clock frequency.

UART PAL, LINFLEXD UART

• For S32R274 & S32R372 (S32R274RRUEVB), LIN1_RX pin on daughter board will not work if J13 and J14 are connected on motherboard.

SBC FS6500

 After transitioning between modes, a delay needs to be added, in order to allow settling and avoid altering frames.

SDADC

The SDADC flags for data valid and watchdog crossover, do not trigger corresponding eTPU channels.

SRX

• If the driver is reinitialized, the peripheral can't resynchronize with the sensor.

SWI2C

- The SWI2C driver doesn't support multi-master mode.
- Detection of bus busy is not supported.
- Baud rate of SWI2C depends on CPU frequency, optimizations, compiler, pull-up resistors that are used, so user should check the baud rate and timing of the SCL and SDA for his application.
- The driver can't ensure a fix baud rate.

SWT

 The driver does not support timer reset in Fixed Execution Address mode and Incremental Execution Address mode (The watchdog is serviced by executing code at the address loaded into the designated IAC register).

TDM

• TDM driver is not supported on Rainier platform.

7.3 Examples

- WKPU example runs in FLASH only if the reset button in pressed after the download to the target.
- Some examples may display warning messages with unresolved includes.
- PASS example can only be run using Lauterbach debug support. S32 Design Studio debug plugins do not support flash access unlocking on secured chips.
- usb_cdc_lwip_mpc5748g is not supported on MPC5748G DEVKIT Rev.D1

7.4 Libraries

AMMCLIB

 The methods displayed in the configurator component might be different from the ones in the actual library.









7.5 Stacks

TCPIP

• The backwards compatibility with the code and component from RTM 3.0.0 is not assured due to the implementation of new features. Please refer to the TCPIP stack release notes document for more information.









8. Compiler options

8.1 GCC Compiler/Linker/Assembler options

Table 8-1 GCC Compiler options

Option	Description
-mcpu=e200z7/e200z4/-mcpu=e200z2	Selects target processor
-funsigned-char	Let the type char be unsigned, like unsigned char
-funsigned-bitfields	Bit-fields are by default signed
-fshort-enums	Allocate to an enum type only as many bytes as it needs for the declared range of possible values.
-ffunction-sections	Place each function into its own section in the output file
-fdata-sections	Place data item into its own section in the output file
-fno-jump-tables	Do not use jump tables for switch statements
-save-temps=obj	Save temp files for debugging purposes
-mbig	Big endian
-mvle	Enable variable-length encoding
-std=c99	Use C99 standard
-msoft-float/-msingle-float	Select the Floating Point type
-g3	Generate debug information
-01	Optimization level one
-Wall	Produce warnings about questionable constructs
-D <cpu_name></cpu_name>	Define a preprocessor symbol for MCU
-DTURN_ON_CPU X	Define for turning on different CPUs. X should be replaced with the desired CPU to be turned on.
-DSTART_FROM_FLASH	Mandatory define when flash target is used
-fno-common	Allocates uninitialized global variables to a section and initializes them to zero at program startup
-msdata=eabi	Enables RAM and ROM SDA with default threshold is 8 byte
-mlra	Use local register allocation
-Dcpux_boot_addr= <address></address>	Optional define when specific boot address is used. X should be replaced with the desired CPU to be updated.

Table 8-2 GCC Linker options

Option	Description
-gc-sections	Remove unused sections
-lc	Link C library
-lgcc	Link libgcc









-lm	Link Math library
-T <linker_script_file.ld></linker_script_file.ld>	Use the specified linker file
entry= Reset_Handler	Make the symbol Reset_Handler be treated as a root symbol and the start label of the application
-WI, -Map= <map_file_name></map_file_name>	Produce a map file
-Wl,defsym,sram_base_addr= <address> -Wl,defsym,sram_size=<size></size></address>	Optional define when specific RAM base address and size is used (if RAM available)
-Wl,defsym,flash_base_addr= <address> -Wl,defsym,flash_size=<size></size></address>	Optional define when specific Flash base address and size is used (if Flash available)
-Wl, defsym,local_dmem_base_addr= <address> -Wl,defsym,local_dmem_size=<size></size></address>	Optional define when specific Local Data Memory base address and size is used (if Local Data Memory available)
-Wl, defsym,local_imem_base_addr= <address> -Wl,defsym,local_imem_size=<size></size></address>	Optional define when specific Local Instruction Memory base address and size is used (if Local Instruction Memory available)

Table 8-3 GCC Assembler options

Option	Description
-mcpu=e200z7/e200z4/-mcpu=e200z2	Selects target processor
-mregnames	Emit register names in the assembly language output using symbolic forms
-mbig	Big endian
-mvle	Enable variable-length encoding
-msoft-float/-msingle-float	Select the Floating Point type
-g3	Generate debug information
-01	Optimization level
-DTURN_ON_CPU0	Mandatory define for the boot core(Z4_0)
-DTURN_ON_CPU X	Define for turning on different CPUs. X should be replaced with the desired CPU to be turned on.









8.2 GHS Compiler/Linker/Assembler options

Table 8-4 GHS Compiler options

Option	Description
-cpu=ppc574xcz4204/-cpu=ppc5748gz210/-	Selects target processor
cpu=ppc5744pz425/-cpu=ppc5744pz425/- cpu=ppc5775kz7260	
gnu_asm	Enables GNU extended asm syntax support
	Generate debug information
-G	
-vle	Enable variable-length encoding
-C99	Use C99 standard
-noSPE	Do not generate SPE or vector floating point instructions
-nostartfiles	Do not add start-up files to link
-fno-common	Allocates uninitialized
-fnone/ -fsoft / -fsingle	Select the Floating Point type
-sda=0	Enables the Small Data Area optimization with a 0 threshold
-dual_debug	Generates the DWARF debugging information in the object file
-Ogeneral	Optimization level
-D <cpu_name></cpu_name>	Define a preprocessor symbol for MCU
-DTURN_ON_CPU X	Define for turning on different CPUs. X should be replaced with the desired CPU to be turned on.
-DSTART_FROM_FLASH	Mandatory define when flash target is used
-sda=8	Enables the Small Data Area optimization with threshold is 8 byte
-Dcpux_boot_addr= <address></address>	Optional define when specific boot address is used. X should be replaced with the desired CPU to be updated.

Table 8-5 GHS Linker options

Option	Description
-nostartfiles	Do not add start-up files to link
-nostdlib	Do not use standard libraries
-entry= Reset_Handler	Make the symbol Reset_Handler be treated as a root symbol and the start label of the application
-T <linker_script_file.ld></linker_script_file.ld>	Use the specified linker file
-Map= <map_file_name></map_file_name>	Produce a map file
-keepmap	Controls the retention of the map file in the event of a link error









-Mn	Generates a listing of symbols sorted numerically by address
-delete -ignore_debug_references	Ignores relocations from DWARF debug sections when using -delete
-Dsram_base_addr= <address> -Dsram_size=<size></size></address>	Optional define when specific RAM base address and size is used (if RAM available)
-Dflash_base_addr= <address> -Dflash_size=<size></size></address>	Optional define when specific Flash base address and size is used (if Flash available)
-Dlocal_dmem_base_addr= <address> -Dlocal_dmem_size=<size></size></address>	Optional define when specific Local Data Memory base address and size is used (if Local Data Memory available)
-Dlocal_imem_base_addr= <address> -Dlocal_imem_size=<size></size></address>	Optional define when specific Local Instruction Memory base address and size is used (if Local Instruction Memory available)
preprocess_linker_directive_full	The C preprocessor preprocesses linker directives files

Table 8-6 GHS Assembler options

Option Description			
-cpu=ppc574xcz4204/-cpu=ppc5748gz210/- cpu=ppc5744pz425/-cpu=ppc5744pz425/- cpu=ppc5775kz7260	Selects target processor		
-preprocess_assembly_files	Enable the run of the C preprocessor over the assembler files		
-nostartfiles	o not add start-up files to link		
-noSPE	Do not generate SPE or vector floating point instructions		
-gnu_asm	Enables GNU extended asm syntax support		
-vle	Enable variable-length encoding		
-C99	Use C99 standard		
-gdwarf-2	Enables the generation of DWARF debugging information		
-sda=0	Enables the Small Data Area optimization with a 0 threshold		
-G	Generate debug information		
-fnone/ -fsoft / -fsingle	Select the Floating Point type		
-dual_debug	Generates the DWARF debugging information in the object file		
-01	Optimization level		
-DTURN_ON_CPU0	Mandatory define for the boot core(Z4_0)		
-DTURN_ON_CPU X	Define for turning on different CPUs. X should be replaced with the desired CPU to be turned on.		









8.3 DIAB Compiler/Linker/Assembler options

Table 8-7 DIAB Compiler options

Option	Description		
-tPPCE200Z210N3VEN:simple/- tPPCE200Z4204N3VEN:simple/- tPPCE200Z4201N3VEN:simple/- tPPCE200Z7260N3VEN:simple	Selects target processor		
-Xdialect-c99	Use C99 standard		
-Xsection-split	Generate a separate section for each function/variable		
N/S	The N in the target processor name shall be replaced with S for software FPU		
-g3	Add debug information to the executable		
-Xdebug-local-all	Emit debug information for unused local variables		
-Xdebug-local-cie	Generate a local Common Information Entry (CIE) for each unit.		
-Xdebug-struct-all	Disable debug optimization of type information		
-Xdebug-dwarf2	Generate DWARF 2 debug information		
-XO	Enable extra optimizations		
-Xsmall-data=0	Disable small data		
-Xsmall-const=0	Disable small const data		
-D <cpu_name></cpu_name>	Define a preprocessor symbol for MCU		
-DTURN_ON_CPU X	Define for turning on different CPUs. X should be replaced with the desired CPU to be turned on.		
-DSTART_FROM_FLASH	Mandatory define when flash target is used		
-Xno-common	Allocates uninitialized global variables to a section and initializes them to zero at program startup		
-Xsmall-data=8	Set size limit for "small data" variables is 8 byte		
-Xsmall-const=8	Set size limit for "small const" variables is 8 byte		
-Dcpux_boot_addr= <address></address>	Optional define when specific boot address is used. X should be replaced with the desired CPU to be updated.		

Table 8-8 DIAB Linker options

Option	Description
-tPPCE200Z210N3VEN:simple/- tPPCE200Z4204N3VEN:simple/- tPPCE200Z4201N3VEN:simple/- tPPCE200Z7260N3VEN:simple	Selects target processor
-Xremove-unused-sections	Removes unused code sections









-lc	Link the standard C library to the project in order to support elementary operations that are used by the drivers		
-lm	Link the standard math library to the project in order to support elementary math operations that are used by the drivers		
ker_script_file.dld>	Use the specified linker file		
-e Reset_Handler	Make the symbol Reset_Handler be treated as a root symbol and the start label of the application		
-m6 <map_file_name></map_file_name>	Produce a linker map		
-Xremove-unused-sections	remove unused section		
N/S	The N in the target processor name shall be replaced with S for software FPU		
-Xpreprocess-lecl	Perform pre-processing on linker scripts		
-MDsram_base_addr= <address> -MDsram_size=<size></size></address>	Optional define when specific RAM base address and size is used (if RAM available)		
-MDflash_base_addr= <address> -MDflash_size=<size></size></address>	Optional define when specific Flash base address and size is used (if Flash available)		
-MDlocal_dmem_base_addr= <address> -MDlocal_dmem_size=<size></size></address>	Optional define when specific Local Data Memory base address and size is used (if Local Data Memory available)		
-MDlocal_imem_base_addr= <address> -MDlocal_imem_size=<size></size></address>	Optional define when specific Local Instruction Memory base address and size is used (if Local Instruction Memory available)		

Table 8-9 DIAB Assembler options

Option Description			
-tPPCE200Z210N3VEN:simple/-	Selects target processor		
tPPCE200Z4204N3VEN:simple/-			
tPPCE200Z4201N3VEN:simple/-			
tPPCE200Z7260N3VEN:simple			
N/S	The N in the target processor name shall be replaced with S for software FPU		
-g3	Add debug information to the executable		
-Xdebug-local-all	Emit debug information for unused local variables		
-Xdebug-local-cie	Generate a local Common Information Entry (CIE) for each unit.		
-Xdebug-struct-all	Disable debug optimization of type information		
-Xdebug-dwarf2	Generate DWARF 2 debug information		
-D <cpu_name></cpu_name>	Define a preprocessor symbol for MCU		
-DTURN_ON_CPU0	Mandatory define for the boot core(Z4_0)		
-DTURN_ON_CPU X	Define for turning on different CPUs. X should be replaced with the desired CPU to be turned on.		
-DSTART_FROM_FLASH	Mandatory define when flash target is used		









9. Acronyms

Acronym	Description
EAR	Early Access Release
JRE	Java Runtime Environment
EVB	Evaluation board
PAL	Peripheral Abstraction Layer
RTOS	Real Time Operating System
PEx	Processor Expert Configurator
PD	Peripheral Driver
S32DS	S32 Design Studio IDE
SDK	Software Development Kit
SOC	System-on-Chip
RTM	Release To Manufacture









10. Version Tracking

Date (dd-Mmm-YYYY)	Version	Comments	Author
28-Apr-2017	1.0	Initial version for EAR 0.8.0	Iulian T.
15-Jun-2017	1.1	Updated known integration issues	Iulian T.
28-Jul-2017	1.2	Update for EAR 0.8.1	Rares V.
14-Dec-2017	1.3	Update for EAR 0.8.2	Cezar D.
28-Mar-2018	1.4	Update for BETA 0.9.0	Cezar D.
19-Jul-2018	2.0	Update for RTM 1.0.0	Cezar D.
17-Sep-2018	2.1	Update for BETA 1.9.0	Cezar D.
11-Dec-2018	3.0	Update for RTM 2.0.0	Cezar D.
21-Mar-2019	3.1	Update for BETA 2.9.0	Vlad L.
24-May-2019	4.0	Update for RTM 3.0.0	Vlad L.
31-Jul-2019	5.0	Update for RTM SR 3.0.1	Rares V

