AN14450 i.MX RT117x ADC Clocks and IO Selection Rev. 2.0 — 5 November 2024

Application note

Document information

Information	Content
Keywords	AN14450, i.MX RT117x, clock sources, ADC
Abstract	This document covers design considerations to avoid possible issues related to synchronicity and noise contamination.



i.MX RT117x ADC Clocks and IO Selection

1 Introduction

The i.MX RT117x chips feature two integrated 12-bit ADCs and a managing peripheral known as the ADC external trigger controller (ADC_ETC). To achieve maximum performance and avoid possible issues, use of these peripherals requires consideration of several design factors.

This document covers design considerations to avoid possible issues related to synchronicity and noise contamination. Under certain circumstances, the flexibility of the ADC_ETC/ADC1/ADC2 setups can have aspects that can affect accuracy and crosstalk, although to a small degree. These effects are easily mitigated with awareness and up-front design.

2 Clocking architecture

The ADC_ETC is well suited for motor controller designs using the PWM peripherals. These designs typically use multiple ADC channels and managing the triggering and FIFO can complicate the software.

2.1 Clock sources

As shown in <u>Figure 1</u>, the ipg_clk (bus_clk) clocks the ADC_ETC. Each ADC has its own clock and can have different clock sources.



3 Clock selection considerations

Selecting the clock sources for the ADCs requires the recognition of the attributes of highly synchronous systems. The ipg_clk and its equivalent clocks synchronize many peripherals. The ipg_clk also clocks the ADC_ETC.

3.1 ADC_ETC and ADC clocks

The ADCs have clock branches and the triggers from the ADC_ETC are synchronized to the ADC clock when a trigger is received. The exact clock-synchronized output depends on the phase relationship between the ipg_clk and the adc_clk. This relationship can change slightly after a reset or power cycle, but remains consistent after the systems are up and running.

The ipg_clk also clocks the external trigger sources to the ADC_ETC (PWM, PIT, and so on).

i.MX RT117x ADC Clocks and IO Selection

3.2 Noise synchronicity

Depending on the layout of the board and how peripherals are used, a small amount of unavoidable noise can be coupled into the ADC conversion. Nevertheless, the ADC still meets its accuracy specifications. This noise from the peripherals can be data or clock noise that is synchronized to the ipg_clk.

If the clock sources (ipg_clk and adc_clk) are in phase and the hardware trigger generated to the ADC_ETC is also derived from the ipg_clk and is repetitive in terms of timing, then the sample times of the ADC are precise from conversion to conversion.

However, this precision in sample times can sometimes cause an issue. The precise timing of the conversion can capture low-level noise that can be synchronized to the ipg_clk. It generates the appearance of a low-level repetitive signal in the ADC data, which can be observed in an FFT of the ADC.

3.3 Crosstalk synchronicity

Another possible issue arises from the signals between the two ADCs. If both ADCs are using the same clock source, it is possible to experience some crosstalk between two ADC inputs (ADC1 and ADC2). The level of crosstalk can vary from reset-to-reset or after a power cycle due to the slight timing variations in the relative clock phases.

The ADC trigger can occur in two cases as follows:

- 1. The ADC_ETC is executing a synchronized conversion, where both ADCs receive a trigger simultaneously. The two channels that are converting simultaneously are possibly susceptible.
- 2. The ADCs are triggered in some other way, at approximately the same time, and a high conversion rate.

4 Mitigation of noise and crosstalk synchronicity

This section explains the method to minimize the effects of noise synchronicity and crosstalk synchronicity requiring careful planning.

4.1 Noise synchronicity mitigation

To avoid the impact of noise synchronicity, a simple method can be used. This effect depends on precise synchronization between the clock sources of the noise, the trigger, and the ADC conversion. Therefore, the easiest approach is to employ a clock source for the ADC that is not phase-locked to the ipg_clk.

The ipg_clk is typically derived from one of the PLLs, which are sourced from the 24 MHz crystal oscillator. All the PLLs are driven from the crystal oscillator, therefore, they are all phase-locked after a reset or power up.

The i.MX RT1170 has two other built-in oscillators, the RC48 and the RC400. These oscillators are internal that are not sourced or referenced to the crystal oscillator. Using either of these two oscillators for the adc_clk prevents the noise synchronicity.

4.2 Crosstalk synchronicity mitigation

A solution similar to the noise synchronicity also helps mitigate the crosstalk synchronicity.

The IOs also play a role in the crosstalk synchronization. Avoid simultaneous conversion for the IOs, GPIO_AD_12 through GPIO_AD_17, inclusive.

Both ADCs share these IOs. They are ADC inputs 3A, 3B, 4A, 4B, 5A, and 5B on each ADC.

To mitigate any changes in crosstalk between the referenced channels, the following two items are recommended:

i.MX RT117x ADC Clocks and IO Selection

- 1. Use IOs GPIO_AD_12 through GPIO_AD_17 for ADC inputs, but do not use them in a mode that is simultaneously triggered with another channel.
- 2. Use a different clock source that is different for each ADC. For example, the use of a PLL on ADC1 and the RC400 on ADC2 eliminates this issue.

5 Conclusions

These minor issues involve low-level signal levels and have minimal impact on most implementations. Addressing these issues requires careful planning and detailed implementation.

6 Revision history

Table 1 summarizes the revisions to this document.

Table 1. Revision history

Document ID	Release date	Description
AN14450 v.2.0	5 November 2024	Updated RT117x to i.MX RT117xMinor editorial changes
AN14450 v.1.0	28 October 2024	Initial public release

AN14450

i.MX RT117x ADC Clocks and IO Selection

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AN14450

AN14450

i.MX RT117x ADC Clocks and IO Selection

Contents

1	Introduction	2
2	Clocking architecture	2
2.1	Clock sources	2
3	Clock selection considerations	2
3.1	ADC ETC and ADC clocks	2
3.2	Noise synchronicity	3
3.3	Crosstalk synchronicity	3
4	Mitigation of noise and crosstalk	
	synchronicity	3
4.1	Noise synchronicity mitigation	3
4.2	Crosstalk synchronicity mitigation	3
5	Conclusions	4
6	Revision history	4
	Legal information	5
	Legal information	

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Document feedback Date of release: 5 November 2024 Document identifier: AN14450