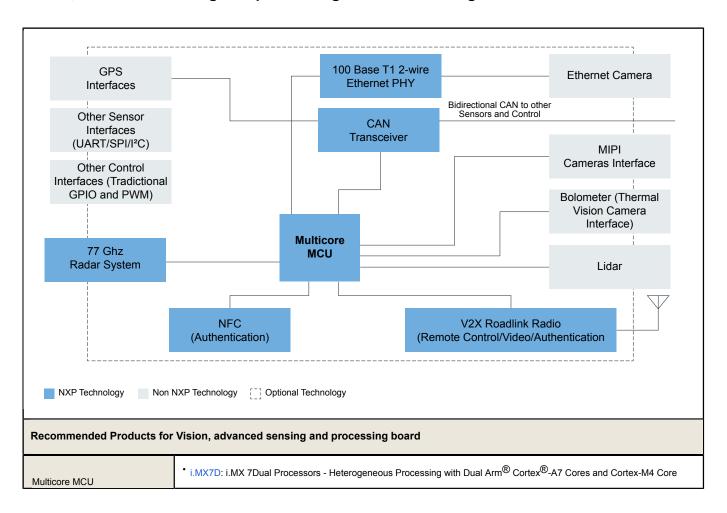


## Vision and Advanced Sensing

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Today's mobile robots (e.g., drones and rovers) need multiple sensor types to determine their location relative to their destination and potential obstacles: inertial sensors and sensor fusion algorithms to accurately know its position in space, or the movement and orientation of an actuator; pressure sensors to measure relative height above ground or as a measurement device for speed or turbulence; and magnetic sensors to provide high reliability angular or rotational measurement. NXP multicore 32 and 64-bit Arm® processors have the embedded hardware IP blocks for vision systems, as well as the processing power and interfaces needed.

## Vision, advanced sensing and processing board Block Diagram



	• i.MX6D: i.MX 6Dual Processors - Dual-Core, 3D Graphics, HD Video, Multimedia, Arm® Cortex®-A9 Core
	* i.MX 6 Processors: i.MX 6 Series Applications Processors: Multicore, Arm <sup>®</sup> Cortex <sup>®</sup> -A7 Core, Cortex-A9 Core, Cortex-M4 Core
	LS1012A: Layerscape® 1012A Low Power Processor
	S32V234: S32V2 Processors for Vision, Machine Learning and Sensor Fusion
Advanced Sensor systems	TEF810X: TEF810x Fully-Integrated 77 GHz Radar Transceiver
	MPL3115A2: Absolute Digital Pressure Sensor (20 to 110 kPa)
CAN Transceiver	TJA144x: Automotive CAN FD Transceiver Family
	TJA1463: CAN Signal Improvement Capability Transceiver with Sleep Mode
	TEF810X: TEF810x Fully-Integrated 77 GHz Radar Transceiver
77 GHz Radar System	S32R294: Radar Microcontroller
	NTAG_I2C: NTAG I²C Plus 2K: NFC Forum Type 2 Tag with I²C Interface
NFC	
	TJA1101: TJA1101B, IEEE 100BASE-T1 Compliant Automotive Ethernet PHY Transceiver
Ethernet Interface	
V2X	V2X Communications: V2X Communications

View our complete solution for Vision and Advanced Sensing.

Note: The information on this document is subject to change without notice.

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